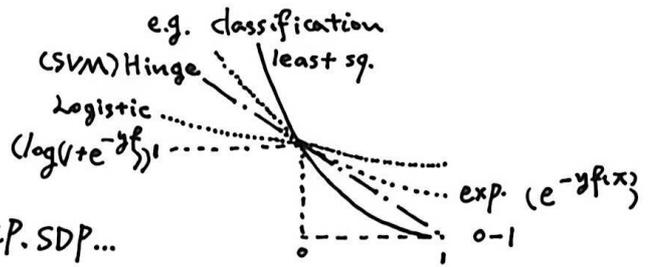


Optimization

- general problem $\min f_0(x)$ s.t. $x \in X$
- (if $\inf_x f_0 = +\infty$: infeasible, $= -\infty$: unbd. from below)
- $X = \{f_i(x) \leq 0, i=1, \dots, m\}$
- $h_j(x) = 0, j=1, \dots, p$
- $f_0: \mathbb{R}^n \rightarrow \mathbb{R}$ LP, QP, SOCP, SDP...
- (structured $f(x) + \lambda g(x)$) IntP, StoP..



- affine set $\alpha x + (1-\alpha)y \in S, \forall x, y \in S, \alpha \in \mathbb{R}$. $\Leftrightarrow S = V + x_0, V$ is a lin. sp.
- convex set $\dots, \alpha \in [0, 1]$. (Pf of \Rightarrow : show $S-S$ is lin. sp.)
- conv. comb. of $\{x_i\}_{i=1}^k$ is $\{y = \sum_{i=1}^k \alpha_i x_i \mid \sum_{i=1}^k \alpha_i = 1, \alpha_i \geq 0\}$. conv. hull $\text{Conv}(S) = \bigcup \{ \text{conv. comb. of } \{x_i\} \}$
- Cone $\alpha x \in K, \forall x \in K, \alpha \in [0, +\infty)$. conic comb. $\{\dots \mid \alpha_i \geq 0\}$. $= \bigcap \text{conv. set } C$. SCC
- polyhedron $\{x \mid Ax \leq b, Cx = d\}$ e.g. (prob) simplex. (halfsp. s, hyperplanes)
- (Euclidean) ellipsoid $\{x \mid (x-\bar{x})' Q (x-\bar{x}) \leq 1, Q \succcurlyeq 0\}$ norm cone $\{(x, t) \mid \|x\| \leq t\}$ is second-ord. cone. Q ($Q = I$ for ball)
- operations preserving conv.: \cap ; affine func. $f(x) = Ax + b$; perspective func., lin. frac. func. e.g. hyperbolic cone $\{x \mid x' P x \leq (c'x)^2, c'x \geq 0, P \succcurlyeq 0\}$; $f(x) = \frac{ax+b}{c'x+d}$
- Sep. hyperplane Thm. C and D are disjoint conv sets., $\exists a \neq 0, b, s.t. C \subset \{a'x \leq b\}, D \subset \{a'x \geq b\}$. Supporting... $\exists a \neq 0, s.t. C \subset \{a'x \leq a'x_0\}$
- convex func $f: X \rightarrow \mathbb{R}$, dom f is conv. and $f(\alpha x_1 + (1-\alpha)x_2) \leq \alpha f(x_1) + (1-\alpha)f(x_2), \forall x_1, x_2 \in \text{dom} f, \alpha \in [0, 1]$. (concave if $-f$ convex) strictly conv. $\dots < \dots$
- (extended value func $\tilde{f}: X \rightarrow \mathbb{R} \cup \{+\infty\}$ with $\tilde{f}(X \setminus \text{dom} f) = +\infty$) α -sublevel set of f
- epigraph $\text{epi}(f) = \{(x, t) \mid f(x) \leq t\}$ Prop. $\text{epi}(f)$ is conv. $\Leftrightarrow f$ is conv. $L_t(f) := \{x \mid f(x) \leq t\}$
- Jessen ineq. $f(\text{ext.})$ is conv. $\Leftrightarrow f(\sum_{i=1}^k \alpha_i x_i) \leq \sum_{i=1}^k \alpha_i f(x_i), \forall \alpha_i \geq 0, \sum_{i=1}^k \alpha_i = 1, x_i \in \mathbb{R}^n$. f conv. $\Rightarrow L_t(f)$ conv.
- (Jacobian) deriv. $\frac{d}{dy} \|f(y) - f(x) - Df(x)(y-x)\| = 0, Dh(x) = Dg(f(x)) Df(x)$ by chain rule.
- gradient $\nabla f(x) = Df(x)'$. (see for matrix form) diff. $h = g \circ f$.
- Hessian $\nabla^2 f(x) = \left(\frac{\partial^2 f(x)}{\partial x_i \partial x_j} \right)_{i,j}$. Prop. f conv. $\Leftrightarrow f(y) \geq f(x) + \nabla f(x)'(y-x), \forall x, y$. (strictly \dots)
- e.g. conv func: $x' Q x$ with $Q \succcurlyeq 0$; $e^x, x^a (x > 0, a \in \mathbb{R} \setminus [0, 1])$; $x \log x; \|x\|_p (p \geq 1); \frac{x^a}{y}$. (first-ord) $\in \mathcal{F}^n$. Prop. 2 cont. diff. $\Leftrightarrow \nabla^2 f(x) \succcurlyeq 0, \forall x$. (second-ord) f is conv. (strictly \dots) (Pf: Taylor's. and $\nabla^2 f$'s cont.)
- operations preserving conv.: \sum or $\int w(y) f(x, y) dy = g(x)$ conv.; $f := \max_i \{f_i(x)\}, g(x) := \sup_{y \in A} f(x, y)$; f_i conv. $(f(x, y)$ conv. in $x, \forall y \in A)$
- e.g.: $\sum_{i=1}^r x_i, \sup_{y \in A} \|x-y\|, \lambda_{\max}(X)$; (if $w(y) \geq 0, f(x, y)$ conv. in x for $\forall y \in A$); $f(x) = h(g_i(x))$ if g_i conv., h conv. \nearrow
- $t \log \frac{t}{x}, \log \sum_{i=1}^m e^{g_i(x)}$; Schur complement, $f(x, y)$ conv. in (x, y) ; or if g_i concave, h conv. \searrow
- $\inf_{y \in C} \|x-y\|; \|X\|_2; \begin{pmatrix} - & & \\ & \geq 0 & \\ & & \end{pmatrix} \succcurlyeq 0$ A conv. $g(x) := \inf_{y \in A} f(x, y)$. $\tilde{f}(h) := f(x_0 + th), \forall x_0 \in \text{dom} f, \forall t \in \mathbb{R}$. iff f is conv.
- $(P(x))^{-1} \ln \det X$ (by ∇^2)

(synthesis: sum, affine, persp.; max & min; mono composition; restriction)

(conjugate $f^*(y) = \sup_x (y'x - f(x))$ is conv. e.g. $\frac{1}{2}y'Q^{-1}y$ to $\frac{1}{2}x'Qx$, $Q \in \mathcal{S}_+^n$)

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convex optimization problem f_0, f_i are conv. and h_j is affine.

$\Rightarrow \forall$ locally optim. solution is global.

(LP) $\min c'x + d$
 s.t. $Gx \leq h,$
 $Ax = b.$

Prop. lin-fac program is equiv. to LP. s.t. $Gy \leq hz,$
 $Ay = bz,$
 $e'y + fz = 1,$
 $z \geq 0.$

$\min_x \frac{c'x+d}{e'x+f}$ s.t. $Gx \leq h,$ $\min_{y,z} c'y + dz$
 $Ax = b. (\Leftrightarrow)$

(QP) $\min \frac{1}{2}x'Px + q'x + r$ s.t. $Gx \leq h,$
 $Ax = b.$ (e.g. least-sq., Markowitz, SVM $\min \frac{1}{2}\|w\|^2 + \mu \sum_i \max\{1 - y_i(w'x_i + b), 0\}$)

(QCQP) $\min \frac{1}{2}x'Px + q'x + r$ s.t. $\frac{1}{2}x'P_i x + q_i'x + r_i \leq 0, i=1, \dots, m$
 $\frac{1}{2}x'A_j x + b_j'x + c_j = 0, j=1, \dots, p$

(SOCP) $\min f'x$ s.t. $\|A_i'x + b_i\| \leq C_i'x + d_i, i=1, \dots, m$
 $Fx = g.$ (general than LP and QCQP)

robust LP

deterministic $\min c'x$ or stochastic $\min c'x$
 s.t. $a_i'x \leq b_i, \forall a_i \in A_i.$ s.t. $P(a_i'x \leq b_i) \geq \gamma_i.$

(e.g. $A_i = \{\bar{a}_i + P_i u \mid \|u\| \leq 1\}$, \Rightarrow SOCP $\bar{a}_i'x + \|P_i'x\| \leq b_i$) (e.g. $a_i \sim \mathcal{N}(\bar{a}_i, \Sigma_i)$, \Rightarrow SOCP $\bar{a}_i'x + \Phi^{-1}(\gamma_i) \|\Sigma_i^{1/2}x\| \leq b_i$)

CVX. Disciplined convex programming ruleset.

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uncons. optimality condition: $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$ is cont. diff., (Pf by 1-Taylor $O(\alpha^2)$)
 if $\exists d \in \mathbb{R}^n$ s.t. $\nabla f(x)d < 0$, then $\exists \alpha_0 > 0$ s.t. $f(x + \alpha d) < f(x), \forall \alpha \in (0, \alpha_0)$

Prop. $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$ is 2 cont. diff., (descent direction) Col. local min \bar{x} has $\nabla f(\bar{x}) = 0.$

\bar{x} is local min $\Rightarrow \nabla f(\bar{x}) = 0, \nabla^2 f(\bar{x}) \succcurlyeq 0.$ Col. f conv. then \bar{x} is global min iff. $\nabla f(\bar{x}) = 0.$
 $\nabla f(\bar{x}) = 0, \nabla^2 f(\bar{x}) \succ 0 \Rightarrow \bar{x}$ is local min.

Fritz-John necessary cond. \bar{x} is a local min of (P) $\min f(x)$
 s.t. $g_i(x) \leq 0, \exists \lambda_i, \nu_j \in \mathbb{R}$ s.t.
 (F) $\mu \nabla f(\bar{x}) + \sum_{i=1}^m \lambda_i \nabla g_i(\bar{x}) + \sum_{j=1}^p \nu_j \nabla h_j(\bar{x}) = 0, h_j(x) = 0$ (Lagrange multiplier)
 $\mu, \lambda_i \geq 0, \lambda_i g_i(\bar{x}) = 0, (\mu, \lambda_i, \nu_j) \neq 0.$ (LICQ)

Karush-Kuhn-Tucker cond. Suppose \bar{x} is regular $\{\nabla g_i(\bar{x})\}_{i \in I} \cup \{\nabla h_j(\bar{x})\}_{j=1}^p$ is lin. ind. where $I = \{i \in \{1, \dots, m\} \mid g_i(\bar{x}) = 0\}$ (active)
 (KKT) $\nabla_x L := \nabla f(\bar{x}) + \sum_{i=1}^m \lambda_i \nabla g_i(\bar{x}) + \sum_{j=1}^p \nu_j \nabla h_j(\bar{x}) = 0,$ (active)
 (μ can be set to 1) (\bar{x}, λ, ν) $\lambda \geq 0, \lambda_i g_i(\bar{x}) = 0.$ + primal cons. $g_i(\bar{x}) \leq 0, h_j(\bar{x}) = 0.$

Global minimum existence Thm. cont. f over $S \neq \emptyset,$ (Weierstrass) compact S, \exists global min & max.
 (coerciveness) $\lim_{\|x\| \rightarrow \infty} f(x) = +\infty,$

KKT for convex: Slater cond. $\exists x' \in S$ s.t. $g_i(x') < 0, \forall i \in I.$ closed S, \exists global min.

(g_i convex and h_j affine) (also a CQ) allow $g_i(x') = 0$ for affine g_i $\Rightarrow \bar{x}$ satisfies KKT. (see for below)

(+ f conv. to be VP.) sufficient cond. $+f$ is conv., if $(\bar{x}, \bar{\lambda}, \bar{\nu})$ is a solution to KKT then it's an optimal to (P). (if g_i concave, \bar{x} satisfies KKT)

e.g. water-filling

$\min \sum_{i=1}^n -\log(x_i + \alpha_i)$ s.t. $x \geq 0, \gamma'x = 1.$

(i.e. (VP) has KKT \Leftrightarrow optim.)

$L(x, \lambda, \nu) = f(x) + \lambda'g(x) + \nu'h(x)$ dual func $\theta(\lambda, \nu) = \inf_{x \in X} L(x, \lambda, \nu)$

(P) $\inf_{x \in X} \sup_{\lambda \in \mathbb{R}_+^m, \nu \in \mathbb{R}^p} L(x, \lambda, \nu)$. since $\forall \varphi, \sup_y \inf_x \varphi(x, y) \leq \inf_x \sup_y \varphi(x, y)$, (Lagrangian) dual problem

Weak duality Thm. \bar{x} to (P), $(\bar{\lambda}, \bar{\nu})$ to (D), (D) $\sup_{\lambda \in \mathbb{R}_+^m, \nu \in \mathbb{R}^p} \theta(\lambda, \nu)$. (many duals since cons. can be treated as X or g, h)
 $\theta(\bar{\lambda}, \bar{\nu}) \leq f(\bar{x})$.

Prop. θ is concave. (Pf: $-\theta$ is p.w. sup.)

Prop. (Fenchel) $\inf_x f_1(x) + f_2(x)$ has dual $\inf_w f_1^*(w) + f_2^*(-w)$. (note for feasible) s.t. $A'y + c \geq 0$ (SDP) $\min \text{tr}(CX)$ s.t. $\text{tr}(A_i X) = b_i, i=1, \dots, m$
 (if it's $f_1(Ax) + f_2(x)$ then dual is $f_1^*(w) + f_2^*(c - A'w)$) (SDP') $\max b'y$ s.t. $C - \sum_{i=1}^m y_i A_i \in \mathcal{S}_+^n$.
 (Pf: let $f_1(y) + f_2(z)$ s.t. $y=z$ or $Az=y$) e.g. LASSO $\min \frac{1}{2} \|Ax - b\|^2 + \|x\|_1$ dual $\max -y'b - \frac{1}{2} \|y\|^2$ s.t. $\|A'y\|_\infty \leq 1$.
 (ADMM) (note conj. of norm s.t. $\|x\|_p \leq 1 \Rightarrow \{0, \dots, 1\}$)

Prop. LP, SOCP, SDP can be formulated as (QP) $\min c'x$ s.t. $q_i'x = b_i, i=1, \dots, m$ closed convex cone
 (Pf by slackness e.g. $Gx + th \leq 0 \Rightarrow s \leq 0, s = Gx + th$) $x \geq \mathcal{K}^0$ (or $x \in \mathcal{K}$ convex cone) $\forall x, \lambda, \nu \in \dots$
 (note conj. of norm s.t. $\|x\|_p \leq 1$)

saddle point $(\bar{x}, \bar{\lambda}, \bar{\nu}) \in X \times \mathbb{R}_+^m \times \mathbb{R}^p$ s.t. $L(\bar{x}, \lambda, \nu) \leq L(\bar{x}, \bar{\lambda}, \bar{\nu}) \leq L(x, \bar{\lambda}, \bar{\nu})$. \Leftrightarrow strong duality.
 iff. (primal feas.) $\bar{x} \in X, g(\bar{x}) \leq 0, h(\bar{x}) = 0$; (dual optim.) $\bar{\lambda} \geq 0, \bar{x} = \arg \min_x L(x, \bar{\lambda}, \bar{\nu})$; $\bar{\lambda}'g(\bar{x}) = 0$. (complementary)

Strong duality for convex: suppose (P) has a solution satisfying Slater's cond. \Rightarrow (D) also has. and (D) = (P).
 (X open & conv., f and g_i conv., h_j affine) (by argmin becomes KKT) & cont. diff.

(synthesis: feasibility \rightarrow truncate. slacken (substitute) (pick off) append (diag.)) (e.g. $(A, b, c) \geq 0 \Leftrightarrow x'Ax + 2b'x + c \geq 0 \forall x. A \geq 0$) Col. g, h affine then (D) = (P).

proper cone conv., closed, (solid) int $\neq \emptyset$, (pointed) $x, -x \in K \Rightarrow x = 0$.
 dual cone $K^* = \{y \mid x'y \geq 0, \forall x \in K\}$ Prop. proper cone's dual is proper.
 K-convex func. $\dots \leq_K \dots$ e.g. $f(x) = x^2 \in \mathcal{S}_+^n$ is \mathcal{S}_+^n -conv. e.g. self-dual cones: orthant \mathbb{R}_+^n ; Lorentz/SO cone $\{(t, x) \mid t \geq \|x\|_2\}$; psd. cone \mathcal{S}_+^n .

SDP relaxation for QCQP: $\min f_0(x) = x'A_0x + b_0'x + c_0$ s.t. $A_i \cdot x + b_i'x + c_i \leq 0$ have the same dual.
 tight cond.: s.t. $f_i(x) = x'A_i x + b_i'x + c_i \leq 0$.
 homogenous $b_i = 0$, only $X \geq 0$, $A_0, A_i \in \mathcal{S}_+^n, i=1, \dots, m$.
 $m \leq 2$ yields $\gamma(X^*) \leq 1, \exists X^* \geq 0$; (S-Lem.) $m \leq 1$ and Slater's holds. (drop the rank cons. ≤ 1)
 if $A_0 \geq \lambda A_1, \exists \lambda > 0$, then $\max \sum_{i=1}^m \lambda_i c_i - \tau$ s.t. $\lambda \geq 0, (\sum_{i=0}^m \lambda_i A_i - \sum_{i=0}^m \lambda_i b_i) \succeq 0, \tau \geq 0$.

SOCP representation: $\min \|Fx + g\| \Rightarrow \min t$ s.t. $\|Fx + g\| \leq t$. conversely need $\exists x, t$ s.t. $f_1(x_1) > 0 \leq t$.
 $\min \frac{\|Fx + g\|^2}{a'x + b} \Rightarrow \min t$ s.t. $a'x + b > 0, (Fx + g)'(Fx + g) \leq (a'x + b)t$. (Slater) Prop. SOCP can be formulated as (SDP) $\min f'x$ s.t. $\begin{pmatrix} c_i'x + d_i & (A_i'x + b_i)' \\ A_i'x + b_i & (c_i'x + d_i)I \end{pmatrix} \succeq 0$.

(RLP) robust $\forall a_i \in \mathcal{E}_i, b_i \in \mathcal{Z}_i$. safe tractable (by Schur's comp) $Fx = g$.
 transform: reformulated as LP; approx. of chance cons. (e.g. Hoeffding?)

LP Strong duality if (P) has an optim. solution x^* , then (D) has a y^* s.t. $C'x^* = b'y^*$.
 (std.) (P) $\min c'x$ (D) $\max b'y$ (bd. from below & feas.)
 s.t. $Ax=b$, s.t. $A'y \leq c$.
 $x \geq 0$.

($\bar{x} \succ_{K^0}$ or $\bar{x} \in \text{int} K$)

(Strong) if (P) bd. from below & strictly feas., then $p^* = d^*$,
 and (D) $\exists \bar{y}$ s.t. $b'\bar{y} = d^*$.

CLP duality (weak) $b'\bar{y} \leq c'\bar{x}$; if (D) bd. from above & strictly feas., $\dots \exists \bar{x}$ s.t. $c'\bar{x} = p^*$.

(P) $\min c'x$ (D) $\max b'y$
 s.t. $Ax=b$, s.t. $-A'y \in K^*$
 (or inn. prod.) $x \in X$.
 Col. when (P) and (D) are both not strictly feas. there exists duality gap. (note inf and sup in P and D) may not be attainable. (KKT can be generalized)

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(f diff.)

iterative algo. for $\min_{x \in \mathbb{R}^n} f(x)$: $x_{k+1} = x_k + t_k p_k$. descent direction e.g. $x \in X, \lambda \in X^*, \lambda'x = 0$. of (P). equiv. to optim.
 $p_k' \nabla f(x_k) < 0$. $\lambda'x = 0$. of (P). equiv. to optim.

gradient descent method $p_k = -\nabla f(x_k)$. (Interpretation: $x_{k+1} = \arg \min_x f(x_k) + \nabla f(x_k)'(x - x_k) + \frac{1}{2} t_k \|x - x_k\|^2$)
 termination criteria e.g. $\|\nabla f\| \leq \epsilon$, $\frac{\|x_{k+1} - x_k\|}{\max\{1, \|x_k\|\}} \leq \epsilon$.

step size rules $t_k \equiv \alpha > 0$; $t_k = \arg \min_{t \geq 0} f(x_k + t p_k)$; (backtracking line search) Armijo.

convergence analysis f is diff., (exact line search) $f(x_k + t_k p_k) \leq f(x_k) + \alpha t_k p_k' \nabla f(x_k)$
 ∇f is L -Lipschitz cont., $t_k = \hat{t} \beta^s, \beta \in (0, 1), \alpha \in (0, 1)$
 e.g. $x'Ax + b'x + c$ is optim. value is bd. $C_L^1(UR)$ (Armijo-Goldstein.)
 Lip. on bd. set and its ∇ is Lip. ∇f is L -Lipschitz cont., $\nabla f(x_k + t_k p_k) \geq \beta \nabla f(x_k)' p_k$ (Wolfe.)

Prop. (quadratic upper bd.)
 if $\nabla f \in C_L^1$, equiv. $i) f(y) \leq f(x) + \nabla f(x)'(y-x) + \frac{L}{2} \|y-x\|^2$
 and when f is 2cont. diff., $\frac{1}{2} x'x - f(x)$ is conv. $\frac{1}{2} \|y-x\|^2$.
 Prop. if f is 2cont. diff., $\nabla f \in C_L^1 \Leftrightarrow \|\nabla^2 f\| \leq L, \forall x$.

(Pf $0 \Rightarrow i) f(y) - f(x) - \nabla f(x)'(y-x) = \int_0^1 (\nabla f(x + t(y-x)) - \nabla f(x))' (y-x) dt$ (stronger than $\nabla^2 f \leq LI$)

Sufficient decrease Lem. $\leq \int_0^1 L t \|y-x\|^2 dt$. (Pf by $\forall h, \frac{\|\nabla^2 f \cdot h\|}{\|h\|} \leq L$;
 $\nabla f \in C_L^1$, then $f(x) - f(x - t \nabla f(x)) \geq t(1 - \frac{L t}{2}) \|\nabla f(x)\|^2$. \leq by $\nabla f(y) - \nabla f(x) = \int_0^1 \nabla^2 f(x + t(y-x)) dt$
 choice $\bar{t} = \frac{1}{L}$ to get $\dots \geq \frac{1}{2L} \|\nabla f(x)\|^2$. (let $y = x - t \nabla f(x)$ in Prop.)

Convergence of grad. method: $f(x_{k+1}) < f(x_k)$ unless $\nabla f(x_k) = 0$, where $f^* = \min_{x \in X} f(x)$, $(k+1)M$
 (of constant \bar{t}) and $\nabla f(x_k) \rightarrow 0, k \rightarrow +\infty$. $M = \bar{t}(1 - \frac{L \bar{t}}{2})$.

... for convex: Prop. conv. f with $\min f$ attained by some x^* , $f(x_k) - f(x^*) \leq \frac{1}{2kt} \|x_0 - x^*\|^2$
 (assume $tL \leq 1$) (Pf: $f(x_{k+1}) \leq f(x^*) + \nabla f(x_k)'(x_k - x^*) - \frac{t}{2} \|\nabla f(x_k)\|^2$)

Prop. (control the grad) Col. iter f of $O(\frac{1}{t})$.
 $\|\nabla f(x_k)\|^2 \leq \frac{L}{kt} \|x_0 - x^*\|^2$ (Pf by Col. $f(x^*) \leq f(x_k) - \frac{1}{2L} \|\nabla f(x_k)\|^2 = f(x^*) + \frac{1}{2t} (\|x_k - x^*\|^2 - \|x_{k+1} - x^*\|^2)$
 and note $f(x_{k+1}) < f(x_k)$.)

for backtracking (let $y = x_k - \frac{1}{L} \nabla f(x_k)$ in upper bd.)
 $(\alpha = \frac{1}{2}) f(x_k) - f(x_k + t_k p_k) \geq t_k \alpha \|\nabla f(x_k)\|^2$, t_k is bd. by $t_{\min} = \min\{\hat{t}, \frac{\beta}{L}\} \leq t_k, \forall k$. (modify the above Props. to get Armijo.)

Prop. (quadratic grad lower bd.)
 if $\nabla f \in C_L^1$, conv. f, then $f(y) \geq f(x) + \nabla f(x)'(y-x) + \frac{1}{2L} \|\nabla f(y) - \nabla f(x)\|^2$. (Pf by using Col. for $g_x(y) = f(y) - \nabla f(x)'y$ which is conv. and $\nabla g_x \in C_L^1$)

... for strongly convex: Prop. μ -sq. conv. f has (quadratic lower bd.)
 $(f(x) - \frac{\mu}{2} x'x \text{ is conv.}) f(y) \geq f(x) + \nabla f(x)'(y-x) + \frac{\mu}{2} \|y-x\|^2$
 $(\mu > 0)$ and when f is 2diff., it has $\nabla^2 f \geq \mu I$.

Prop. (lin. convergence) $f(x_k) - f(x^*) \leq (1 - \frac{\mu}{L})^k (f(x_0) - f(x^*))$.
 (Pf by $f(x^*) \geq f(x) - \frac{1}{2\mu} \|\nabla f(x)\|^2$ by lower bd.) (also for Armijo. with $\alpha = \frac{1}{2}, \hat{t} \leq 1$)

(synthesis: condition number $\frac{L}{\mu}$. iters to $f_k - f^* \leq \epsilon$ is at most $\approx \frac{1}{\mu} \log \frac{f_0 - f^*}{\epsilon}$,)
 (slow and may depend on scaling) for constant step size.

(convergence rate $e_k = \|x_k - x^*\|$ or $\|f_k - f^*\|$, $\mu := \lim_{k \rightarrow \infty} \frac{e_{k+1}}{e_k} = \begin{cases} 1 & \text{sub-lin.} \\ \in (0,1) & \text{lin.} \\ 0 & \text{super-lin.} \end{cases}$)
 e.g. quadratic in super-lin. $\lim_{k \rightarrow \infty} \frac{e_{k+1}}{e_k^2} = \mu_2 > 0$.

(supplements: double sufficient decrease $\underline{\Delta}_m$. ($\pm L \leq 1$)
 if $\nabla f \in C^1$, conv. f, then $f(x_k) - f(x_{k+1}) \geq \frac{t}{2} \|\nabla f(x_k)\|^2 + \frac{t}{2} \|\nabla f(x_{k+1})\|^2$.
 low bd. $\underline{\Delta}_f \rightarrow$ upp. bd. Δ_f
 : Δ_f
 conv. monotonicity. ($\pm L \leq 2$) $\nabla f(x_k) \cdot \nabla f(x_{k+1}) \geq 0$ and $\|\nabla f(x_{k+1})\| \leq \|\nabla f(x_k)\|$.)

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(affine invariance)

Newton step $x_{k+1} = x_k - \nabla^2 f(x_k)^{-1} \nabla f(x_k)$ (quadratic approx.) solve $\nabla f_k + \nabla^2 f_k p_k = 0$. (Cholesky $\frac{1}{2}n^3$, $\nabla^2 f = LL^T$.
 pure Newton may diverge. damped $\sim f(x_k) - f(x_k + t_k p_k)$ ($\nabla^2 f > 0$, decrease) Newton-CG...
 convergence analysis. f is 2 cont. diff. (Armijo) $\geq \alpha t_k (\nabla f_k^T \nabla^2 f_k^{-1} \nabla f_k)$. ($\gamma_k \in (0,1)$ lin. inexact $\|x_k\| \leq \gamma_k$.
 (∇f is M -lip. and $MI \geq \nabla^2 f \geq mI$. (otherwise $t_k \leftarrow \beta t_k$, $t_0 = 1$) $\gamma_k \rightarrow$ superlin. $O(\|\nabla f\|)$ is quad.) $\|\nabla f_k\|$
 sq. conv. with m) $\nabla^2 f$ is L -lip. cont. Prop. f is 2 cont. diff., $\nabla^2 f$ is 2-lip. $\frac{L}{\delta} \|y - x\|^3$
 $\exists 0 < \gamma \leq \frac{m^2}{L}$, $\gamma > 0$ s.t. $\left\{ \begin{array}{l} \text{phase 1 (sublin.) } f_{k+1} - f_k \leq -\gamma \|\nabla f_k\| \Rightarrow \gamma. \text{ (damped)} \\ \text{phase 2 (quad) } t_k \equiv 1, \frac{L}{2m^2} \|\nabla f_{k+1}\| \dots < \gamma. \text{ (pure)} \end{array} \right.$

Adv. fast conv., affine invar. (not conditioning) or high dim.

Disadv. $\nabla^2 f$ and solve $O(n^3)$, memory $O(n^2)$. $\min m_k(p) \triangleq f_k + \nabla f_k^T p + \frac{1}{2} p^T B_k p$. $p_k = -B_k^{-1} \nabla f_k$ let B satisfies approx $B_k \rightarrow \nabla^2 f(x_k)$. (auto) $\nabla m_{k+1}(0) = \nabla f(x_{k+1})$, curvature condition $B_{k+1} s_k = y_k$.
 quasi-Newton method $H_k \rightarrow \nabla^2 f(x_k)^{-1}$. $\nabla m_{k+1}(-t_k p_k) = \nabla f(x_k)$. (for pos. def. of B) $s_k^T y_k > 0$.

DFP update $\min \|B - B_k\|_{F,W}$ B_k s.t. $B = B^T$, $B s_k = y_k$.
 $\Rightarrow B_{k+1} = (I - \rho_k y_k s_k^T) B_k (I - \rho_k s_k y_k^T) + \rho_k y_k y_k^T$, curv. condition in quasi-N.
 $\rho_k = \frac{1}{y_k^T s_k}$. SMW formula yields $H_{k+1} = H_k - \frac{H_k y_k y_k^T H_k}{y_k^T H_k y_k} + \frac{s_k s_k^T}{y_k^T s_k}$. (pf: $y_k^T s_k \geq (c_2 - 1) t_k \nabla f_k^T p_k > 0$)
 (B = A + UCV^T) $B^{-1} = A^{-1} - A^{-1} U (C^{-1} + V^T A^{-1} U)^{-1} V^T A^{-1}$. BFGS update H_k . exchange B with H, y with s.

... for BFGS: (Pf by Zoutendijk's Thm.) than BFGS starts $t_k = 1, c_1 = 10^{-4}, c_2 = 0.9$,
 f is 2 cont. diff. and $\{x: f(x) \leq f(x_0)\}$ convex, $mI \leq \nabla^2 f \leq MI, \forall x \in \{ \}$. $H_0 = \frac{y_0^T s_0}{y_0^T y_0} I$.

L-BFGS. $H_{k+1} = (I - \rho_k s_k y_k^T) H_k (I - \rho_k y_k s_k^T) + \rho_k s_k s_k^T$ Store (up to m steps) s_i, y_i . $O(mn)$.
 (two-loop recursion algo.) compact representation. ~

BB gradient method. $-t_k \nabla f_k$ approx. $-\nabla^2 f_k^{-1} \nabla f_k$. $\min \|s_{k-1} - D_k y_{k-1}\|$ yields $t_k = \frac{s_{k-1}^T y_{k-1}}{y_{k-1}^T y_{k-1}}$.
 trust region. $\min m_k(p_k)$ (approx. secant eq.) $\min \|D_k^{-1} s_{k-1} - y_{k-1}\|$ $t_k = \frac{s_{k-1}^T s_{k-1}}{s_{k-1}^T y_{k-1}}$.
 s.t. $\|p_k\| \leq \Delta_k$. (bd. from line search) ($D_k = t_k I$ for H_k) (adjusting Δ in steps)

Cubically reg. Newton. (like grad. method) use $\dots + \frac{L}{6} \|x - x_k\|^3$ in Prop. to min. $O(\epsilon^{-\frac{3}{2}})$.

Gauss-Newton method. $\min_x \frac{1}{2} \|g(x)\|^2$. cont. diff. $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$. $x_{k+1} = x_k - t_k (J_k^T J_k)^{-1} J_k^T g_k$.
 linear approx. $\min \frac{1}{2} \|g(x_k) + J_k(x - x_k)\|^2 + \text{stepsize}$ to get (i.e. Newton's. drop term in $\nabla^2 f$)
 (esp. $g(x) \approx 0$)
 $L M_{s_i}^T J_k + \rho_k I$ if not full-rank)

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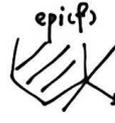
• subgradient. $f(y) \geq f(x) + g'(y-x) \cdot \forall y$.

Calculus rules: $a > 0, \partial(a f) = a \partial f$.

$$\partial(c f_1 + f_2) = \partial f_1 + \partial f_2$$

affine. $g(x) := f(Ax+b), \partial g = A \partial f(Ax+b)$.

(fin.) p.w. max. $f = \max_{i=1, \dots, m} f_i(x), \partial f = \text{Conv} \cup \{ \partial f_i(x) \mid f_i(x) = f(x) \}$.



(2) subdiff. $\partial f(x) = \{ g \mid g'(y-x) \leq f(y) - f(x), \forall y \}$.

Prop. i) $0 \in \partial f(x_{\min})$. ii) if f is conv. and $\text{dom}(f)$ open, $\partial f(x) \neq \emptyset$ b.d.

iii) if f diff. $\partial f(x) = \{ \nabla f(x) \}$.

e.g. $f(x) = \|x\|_2, \partial f = \begin{cases} \frac{x}{\|x\|} & x \neq 0 \\ \{0\} & x = 0 \end{cases}$

$f(x) = \frac{1}{2} \|x-y\|_2^2 + \lambda \|x\|_1$ (soft-thres.)
 $\partial f = \begin{cases} x-y & x < 0 \\ [x-y, x+y] & x = 0 \\ x-y & x > 0 \end{cases}$

nondiff. KKT (similar) min fo s.t. $f_i \leq 0$.

if strong duality, $f_i^* \leq 0; \lambda^* \geq 0; 0 \in \partial f_0(x^*) + \sum \lambda_i^* \partial f_i(x^*); \lambda_i^* f_i(x^*) = 0$.

esp. min $f(x)$, let $I_c = \begin{cases} 0 & x \in C \\ \infty & \text{else} \end{cases}$, then $0 \in \partial f(x) + \partial I_c(x)$.

e.g. proj. $\min_y \frac{1}{2} \|y-x\|_2^2 + I_c(y)$,
 i.e. $(x-y)'(x-y) \leq 0, \forall y \in C$.



• subgradient method. proj. conv. f on closed conv. X. $y_{k+1} = x_k - \alpha_k g_k, g_k \in \partial f(x_k)$. Lem. $\forall x \in X, y$,

convergence analysis: conv. f on \mathbb{R}^n .

$$x_{k+1} = \Pi_X(y_{k+1}), \quad \|\Pi_X(y) - x\|^2 \leq \|y - x\|^2$$

not descent. $f(x^*) = \inf f > -\infty$.

Prop. $\|g\| \leq G, \forall g \in \partial f \Leftrightarrow f$ is G -Lip.

$f_{bs} \triangleq \min_i f_i(x)$, then

$$\|g\| \leq G, \forall g \in \partial f.$$

(Pf of \Rightarrow : $-g_x'(y-x) \geq f(x) - f(y) \geq g_y'(x-y)$.)

const. d: $f_{bs}^k - f^* \leq \frac{R^2 + G^2 k d^2}{2kd} \rightarrow \frac{G^2 d}{2}, \alpha_0 = \frac{R}{G \sqrt{k}}, O(\frac{RG}{\sqrt{k}})$. (synthesis: nonsmooth + conv.)

const. length $\alpha \|g\|$: $\leq \frac{R^2 + G^2 k}{2\gamma k} G \rightarrow \frac{G\gamma}{2}, \alpha_0 = \frac{R}{\sqrt{k}}$. (R is dom f's diam.)

Polyak's step size. $\alpha_k = \frac{f_k - f^*}{\|g_k\|^2}$.

(when f^* is known.) it also, $\leq \frac{RG}{\sqrt{k}}$.

e.g. find point in $\cap C_j$ i.e. $\min_x (\max_j d_j(x))$, use subgrad

(alternating projs.) $g_k = \frac{x_k - P_{C_j}(x_k)}{\| \dots \|_2}$ (C_j is the farthest set), $\alpha_k = f(x_k)$,
 i.e. $x_{k+1} = P_{C_j}(x_k)$.

smooth (Lip ∇) + conv. $\frac{GD}{\sqrt{k}}$;
 sm. + sq. conv. $(1 - \frac{\mu}{L})^k$; nonconv. $\frac{\dots}{\sqrt{k}}$;
 nonsm. + sq. conv. $\frac{2G^2}{\mu k}$; Nestorov. $\frac{2LD^2}{k^2}$ (in sm. + conv.)



e.g. $Ax = b, x \geq 0$.

$$S_1 = \{x : Ax = b\}, S_2 = \mathbb{R}_+^n$$

$$\text{then } x_{k+1} = (x_k - A'(AA')^{-1}(Ax_k - b))^+$$

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• $f = g + h$, diff. g ($\text{dom}(g) = \mathbb{R}^n$), nondiff. but conv. h.

when $\min_{x \in X} g(x)$, interpretation of proj. grad. $\min_u g(x_{k-1}) + \nabla g(x_{k-1})'(u - x_{k-1}) + \frac{1}{2t_k} \|u - x_{k-1}\|^2 + I_X(u)$.

here $\min_x f(x)$, similarly $\min_u \dots + h(u)$ i.e. $\min_u \frac{1}{2t_k} \|u - (x_{k-1} - t_k \nabla g(x_{k-1}))\|^2 + h(u)$

prox. mapping operator

(local $g(u)$ around x_{k-1})

$$= \text{prox}_{t_k h}(x_{k-1} - t_k \nabla g_{k-1}). \text{ (e.g. Lasso)}$$

$$\text{prox}_h(x) = \arg \min_u \frac{1}{2} \|u - x\|^2 + h(u). \text{ e.g. } h = I_C, \text{ proj. on } C; h = \|x\|_1 \cdot \lambda, \text{ soft-thres. (shrinkage);}$$

... of prox. grad.: g is m -sq. conv. and ∇g L -Lip. $h = \|x\|_2 \cdot \lambda, \text{ prox}_h(x) = \begin{cases} (1 - \frac{t}{\|x\|_2})x & \|x\|_2 \geq t \\ 0 & \|x\|_2 < t \end{cases}$;

(Pf:) lin. conv., $O(\frac{1}{k})$ with $t_k \equiv \frac{1}{k}$.

$$C = \text{SOC} \{ (x, t) \in \mathbb{R}^{n+1} : \|x\|_2 \leq t \}, P_C(v, s) = \begin{cases} 0 & \|v\| \leq -s \\ (v, s) & \|v\| \leq s \\ \frac{1}{2} (1 + \frac{s}{\|v\|}) (v, \|v\|_2) & \|v\| > |s| \end{cases}$$

verify $G_t(x) \in \nabla g(x) + \partial h(x - t G_t(x))$ (note but $G_t(x)$ is not subgrad.)

and $G_t(x_{\min}) = 0$. use g 's L -upper bd. for $x - t G_t(x)$, g 's m -lower bd. and ∂h 's def. to get

line search.

$$\text{Prop. } f(x - t G_t(x)) \leq f(x) + G_t(x)'(x - x) - \frac{t}{2} \|G_t(x)\|^2 - \frac{m}{2} \|x - x\|^2$$

Col. let $z = x, f(x') \leq f(x) - \frac{t}{2} \|G_t\|^2$; let $z = x^*, f' - f^* \leq \frac{1}{2t} (\|x - x^*\|^2 - \|x' - x^*\|^2)$.

(to satisfy g 's bd with $\alpha = \frac{1}{2}$) $f_k - f^* \leq \frac{1}{2kt} \|x_0 - x^*\|^2, \|x_k - x^*\|^2 \leq (1 - \frac{m}{L})^k \|x_0 - x^*\|^2$. (from above)

(same for $\frac{1}{2kt_{\min}} (1 - m t_{\min})$) f_k is decreasing and $G_{t_k}(x_k) \rightarrow 0, k \rightarrow \infty$. (same as grad. method) $h \equiv 0$

(g 's bd. i.e. sufficient decrease) faster than subgrad. useful when prox_h simple.